

# Preferred citation style for this presentation

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[Animated online version](#)

# The IVT Baseline Scenario: Current version and outlook

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# Demographics

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- Microcensus Mobility and Transport 2010
  - 2015 Version available
- Generalized Ranking
  - Implementation Kirill Müller

# Demographics



Bösch et al.  
2016

# Activity Chains

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- Hot-Deck Matching with certain attributes
  - Sampling from Microcensus
- Long-term behavioural change
  - Input scenario vs. dynamic rescheduling?
  - Activity-based model?

# Primary Locations

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- Structural Survey 2010 - 2012
- Enterprise Census 2012
- Sampling from commuters matrices (municipalities)
- Assignment by home - workplace distance  
(consistency with activity chains)
- *So far no validation available*

# Secondary Activity Facilities

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- Enterprise Census 2012
  - Conversion: Patrick Bösch
- Capacities
  - Rather undocumented
  - Not used yet

# Secondary Activity Assignment

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- New sampling approach (Hörl)
- Aim: Location choices that are consistent with activity plans
- No capacity constraints yet
- Iterative process:
  - Generation of feasible “unsnappped” distance chains
  - Discretization of locations



# Secondary Activity Assignment

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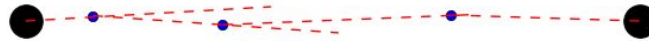
## Algorithm 1: Sampling of feasible distances tours

1. Construct distribution of distances for 5min bins of travel times for each mode
2. Per agent:
  - a. Sample a chain of distances based on travel times in the plan
  - b. Use gravity model to relax locations in  $\mathbb{R}^2$
  - c. If chain is not feasible, continue with (a)
  - d. Abort if maximum number of iterations is reached  $\rightarrow$  Infeasible

# Secondary Activity Assignment

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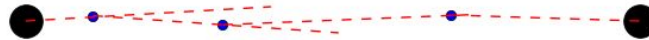
## Algorithm 1: Sampling of feasible distances tours



# Secondary Activity Assignment

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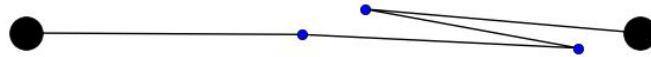
## **Algorithm 2: Spatial discretization**

1. Sample a continuous chain (**Algorithm 1**)
2. Discretize locations (based on available facilities)
3. If discretization error is too large, continue with 1
4. Abort if maximum number of iterations is reached

# Secondary Activity Assignment

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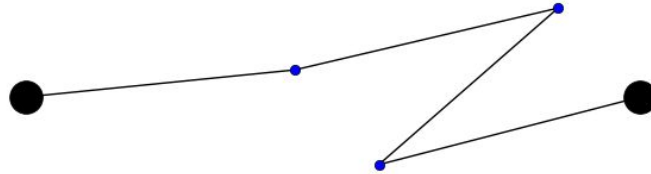
## Algorithm 2: Spatial discretization



# Secondary Activity Assignment

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## Algorithm 2: Spatial discretization

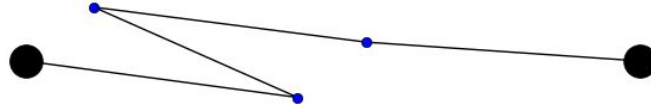




# Secondary Activity Assignment

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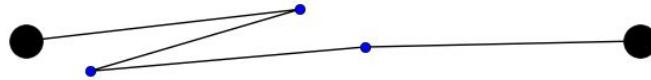
## Algorithm 2: Spatial discretization



# Secondary Activity Assignment

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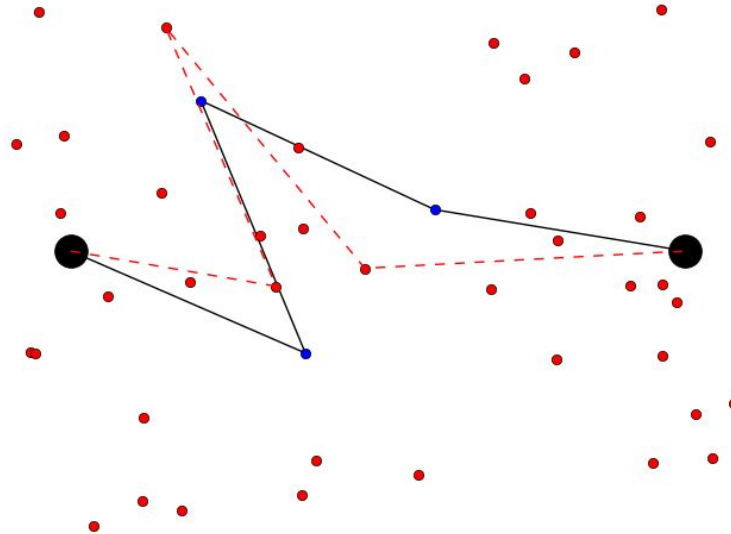
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# Secondary Activity Assignment

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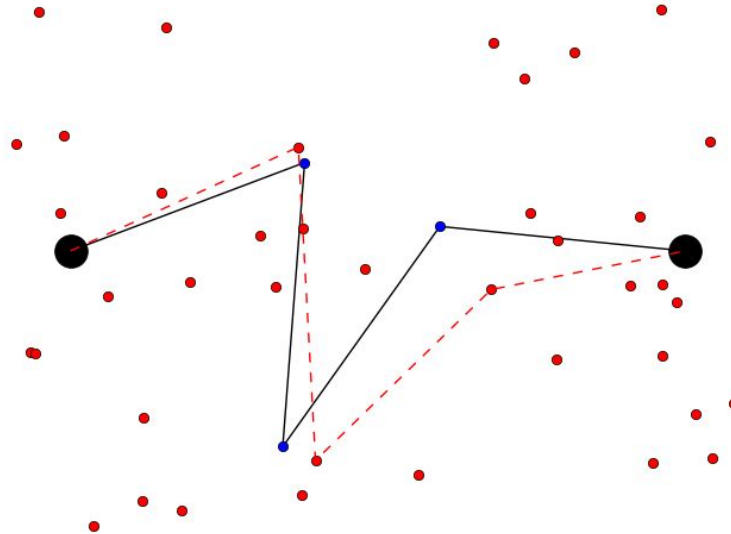
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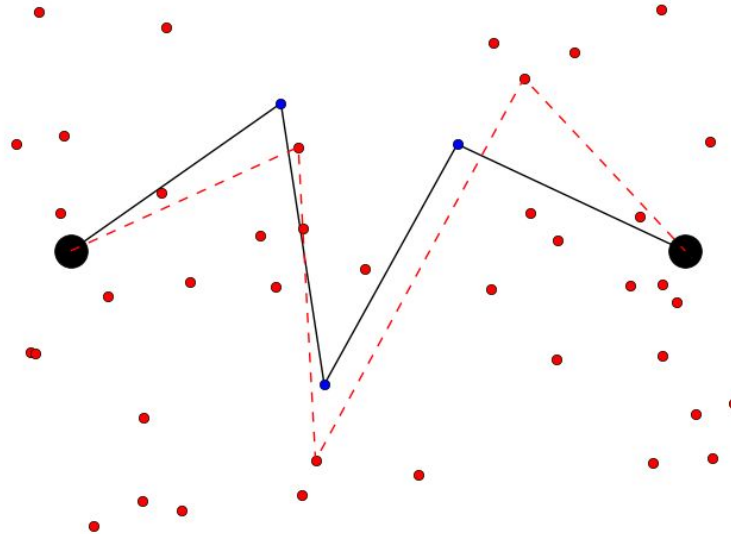
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# Secondary Activity Assignment

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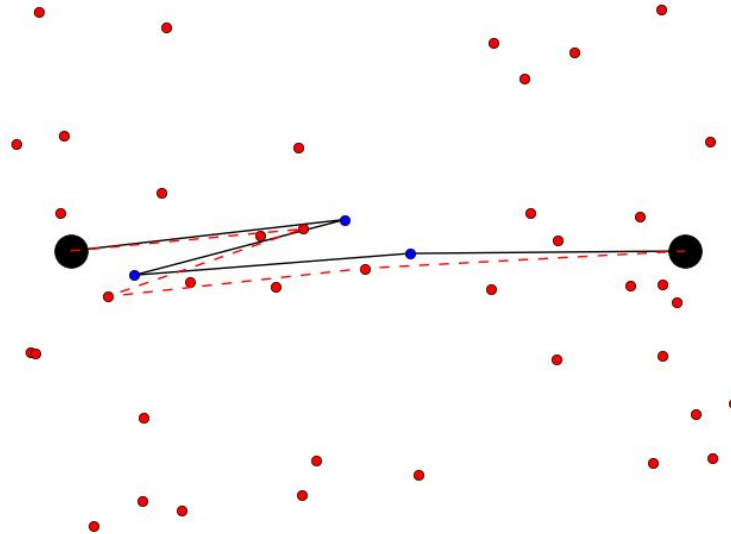
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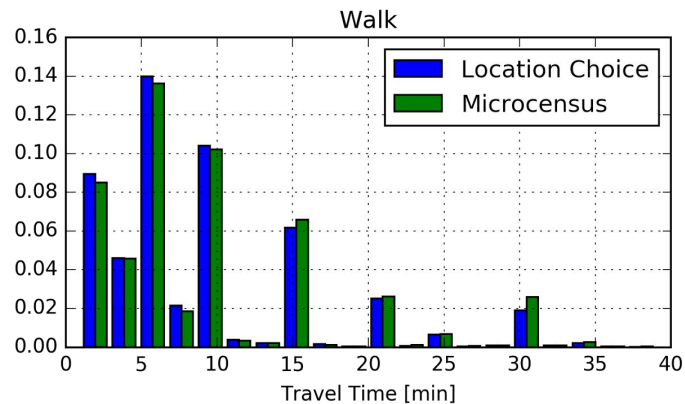
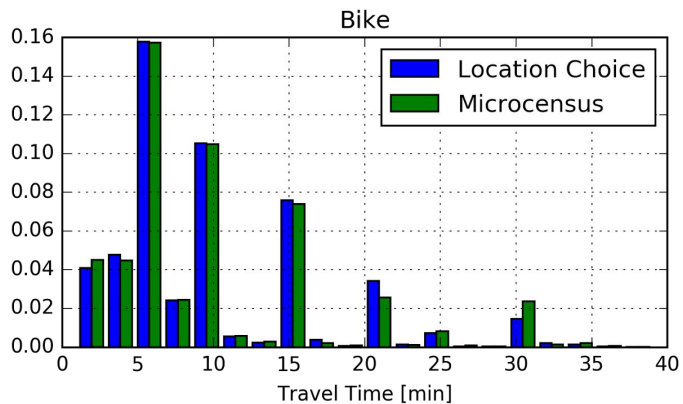
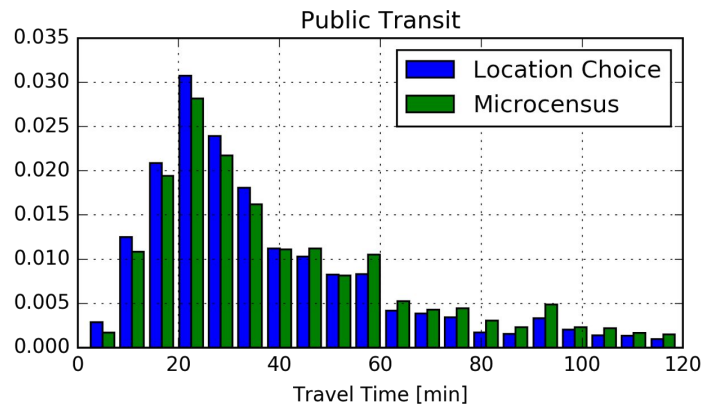
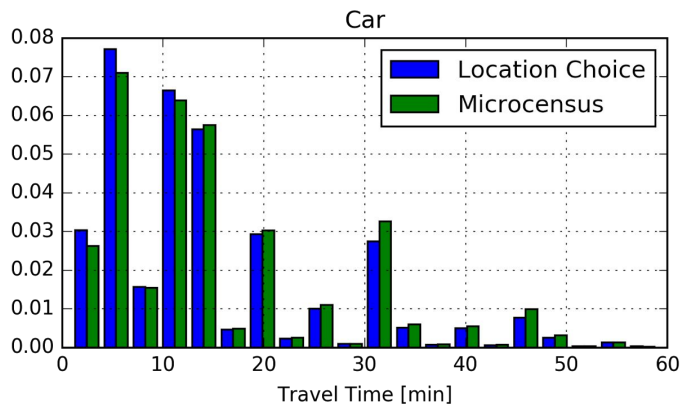
# Secondary Activity Assignment

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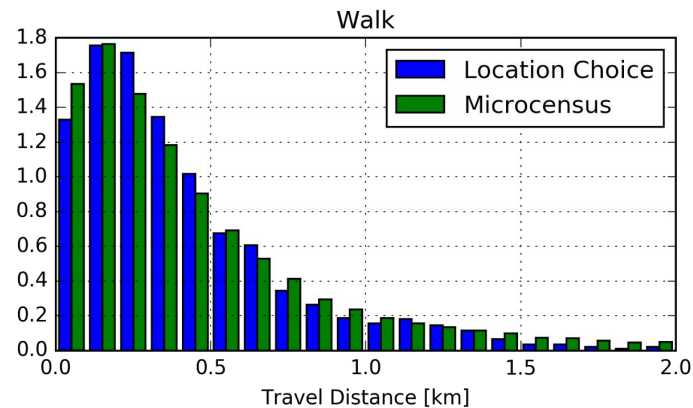
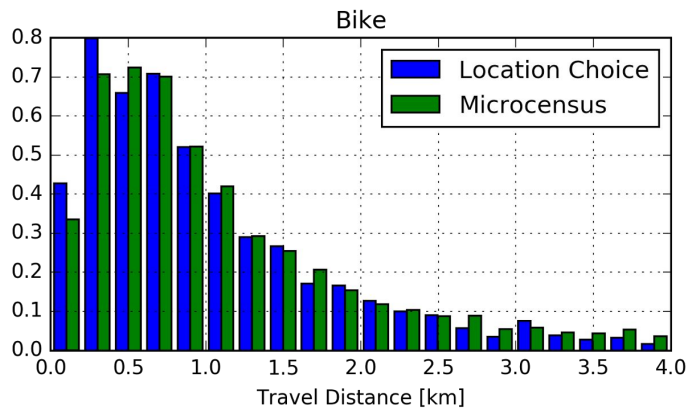
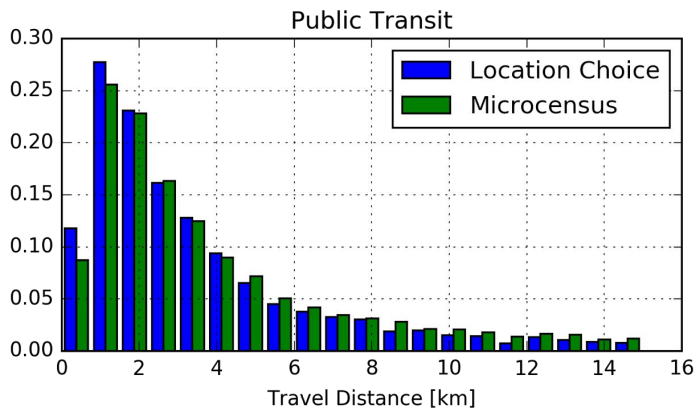
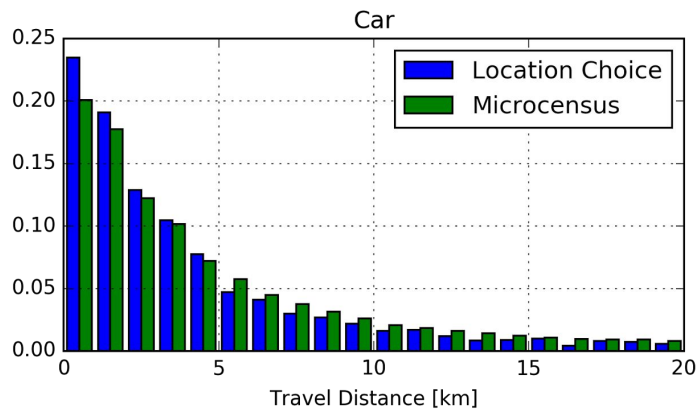
## Algorithm 2: Spatial discretization



# Secondary Activity Assignment



# Secondary Activity Assignment





# Mode Choice

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- Problems
  - Currently: Based on whole subtours
  - One choice per 10% of iterations, long runtime
  - Public Transport can be “walk”
  - Connection between activities and legs?

# Mode Choice

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- New mode choice model (Hörl & Balac)
  - Choice of complete trip chains (structural constraints)
  - Mode choice model based on Microcensus (Basil Schmid)
  - Mode choice model based on Automated Vehicle survey (Felix Becker)

# Mode Choice

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## **Algorithm: Mode choice by chain**

1. Construct all feasible mode chains for an agent
2. Compute probability for each trip
3. Compute weights / joint probability for each chain
4. Perform choice
  - a. Either     Select chain with largest weight
  - b. Or         Treat as categorical distribution and sample

# Mode Choice



$P(\text{Chain 1}) \sim P(\text{Leg 1} = \text{car}) * P(\text{Leg 2} = \text{car}) * \dots$



$P(\text{Chain 2}) \sim P(\text{Leg 1} = \text{pt}) * P(\text{Leg 2} = \text{pt}) * \dots$



$P(\text{Chain 3}) \sim P(\text{Leg 1} = \text{pt}) * P(\text{Leg 2} = \text{walk}) * \dots$



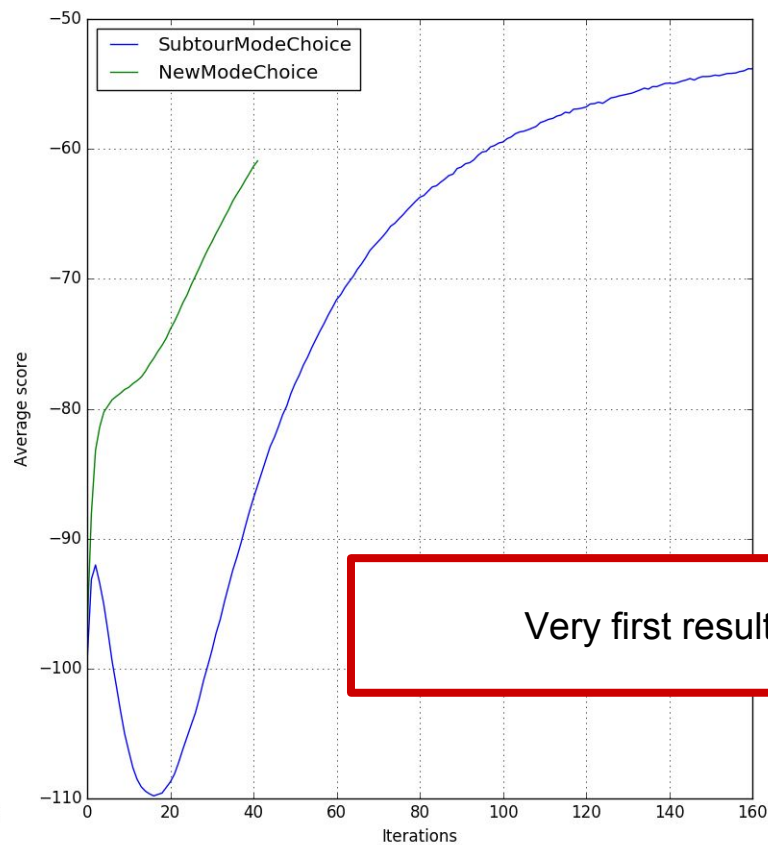
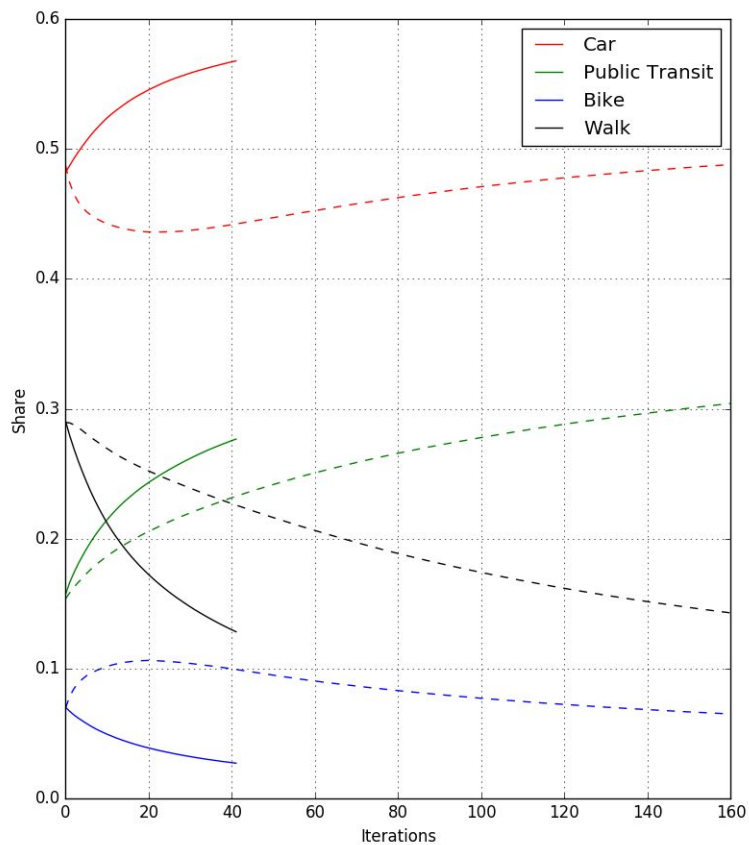
$P(\text{Chain 4}) \sim P(\text{Leg 1} = \text{walk}) * P(\text{Leg 2} = \text{pt}) * \dots$



$P(\text{Chain } u)$

$\text{Modes}^{\text{Legs}} - n$

# Mode Choice



Very first results

## Additional Remarks

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- Temporal shifting of activity plans
- Simulated travel times
- Public Transit (currently fallback to teleportation)

# Outlook

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- Setup of validation pipeline
  - “Unit tests for scenarios”
- Open Switzerland Scenario
- Future scenarios (ARE, ...)

# Questions?

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# References

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- Bösch, P., K. Müller, F. Ciari (2015) The IVT Baseline Scenario, Presented at the 16th Swiss Transport Research Conference, May 2016, Ascona.