

The impact of autonomous vehicles on accessibilities in a metropolitan region

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Focus of this study

- Autonomous cars
 - An upcoming means of travel
- Accessibilities
 - An upcoming means of transport policy analysis

AUTONOMOUS VEHICLES

Autonomous vehicles

- Arguably great impact on patterns of movement
- Might to change the way people accommodate their wish to participate in activities
- Potential to increase mobility options and flexibility
- Stronger reliance of transport systems on autonomous vehicles might lead to problems in terms of equity

Some Facts and Expectations

- Developments in AV technology will sooner or later lead to new taxi-like services
- Service provision is expected to be very cheap
- Private (self-driven) cars
 - Usership may decline if AV services are as reliable as car trips
- Public transport
 - Ridership may decline if AV services are as cheap as PT

ACCESSIBILITIES

What is the goal of transport and land use planning?

What is the goal of transport and land use planning?

- *Improve mobility?*
 - Increase in the territory that can be reached for a given investment of time and money
- *Improve accessibility?*
 - Increase in the (value of) destinations that can be reached for a given investment of time and money

(Definitions by Jonathan Levine, NECTAR Cluster 6 Workshop)

Example



Example



Example



Example



Example



What is the goal of transport and land use planning?

- More Destinations
 - -> Better
- A destination more easy to reach
 - -> Better

An econometric accessibility measure

- Utility at location i gained from opportunities at j:
- $U_{ij} = V_{\text{perf}} + V_{ij} + \varepsilon_{ij}$
 - V_{perf} = Utility of activity no matter where
 - V_{ij} = Utility of journey from i to j (usually negative)
 - ε_{ij} = Variation / person- or opportunity-specific corrections to V_{perf} and V_{ij}
- Assumption: Distribution of ε_{ij} is IID-Gumbel

$$P_i(j) = \frac{e^{\mu*(V_{\text{perf}}+V_{ij})}}{\sum_j e^{\mu*(V_{\text{perf}}+V_{ij})}}$$

- Expected Maximum Utility (EMU)

$$E(U) = \frac{1}{\mu} * \ln \sum_j e^{\mu*(V_{\text{perf}}+V_{ij})}$$

An econometric accessibility measure

- Expected Maximum Utility (EMU)

$$E(U) = \frac{1}{\mu} * \ln \sum_j e^{\mu * (V_{perf} + V_{ij})}$$

$$E(U) = V_{perf} + \frac{1}{\mu} * \ln \sum_j e^{\mu * V_{ij}}$$

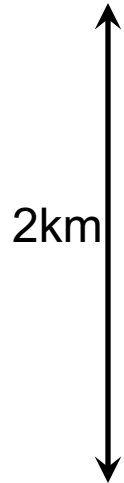
$$E(U) = V_{perf} + A_i \quad \text{with} \quad A_i = \frac{1}{\mu} * \ln \sum_j e^{\mu * V_{ij}}$$

- If $\mu=1$ and $V_{ij} = -C_{ij}$ C_{ij} = Generalized costs to get from i to j

$$A_i = \ln \sum_j e^{-C_{ij}}$$

Accessibility computation example

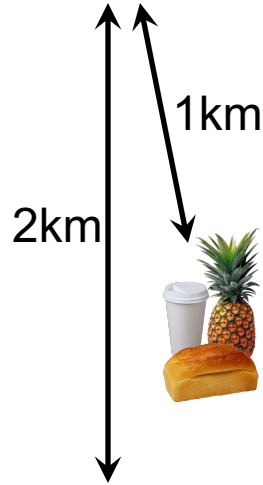
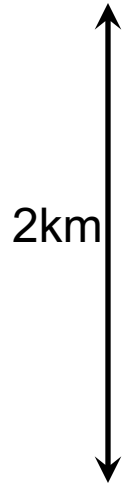
$$A_i = \ln \sum_j a_j \cdot e^{-c_{ij}}$$



$$A_i = \ln(e^{-2})$$
$$= -2$$

Accessibility computation example

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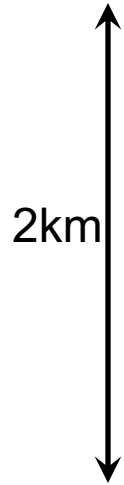
$$A_i = \ln(e^{-2} + e^{-1})$$

$$= \ln(0.135 + 0.368)$$

$$= -0.687$$

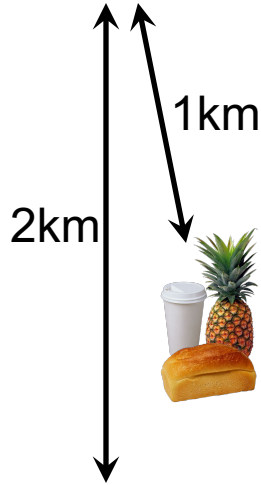
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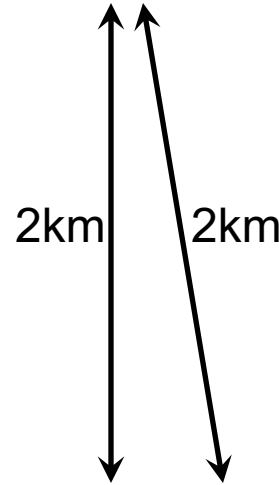
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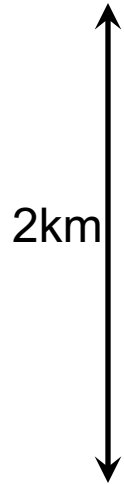
$$A_i = \ln(e^{-2} + e^{-2})$$

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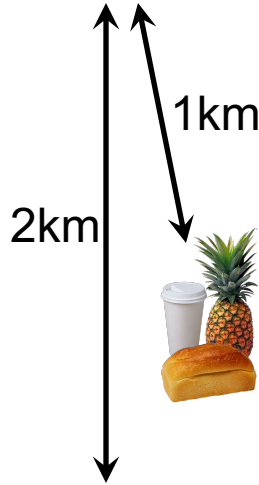
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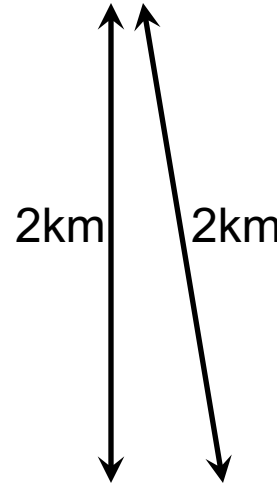
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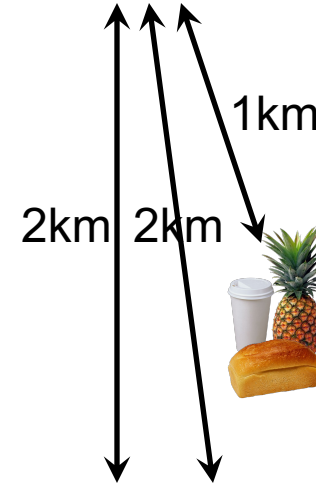
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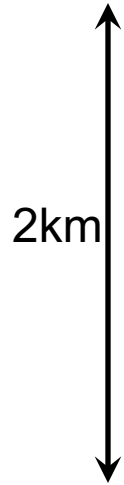
$$A_i = \ln(e^{-2} + e^{-2} + e^{-1})$$

$$= \ln(0.135 + 0.135 + 0.368)$$

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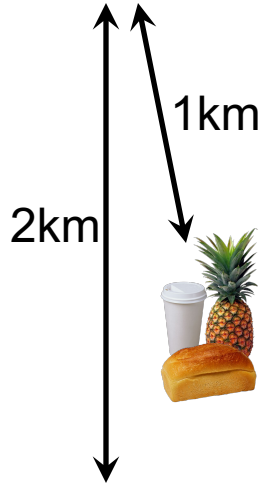
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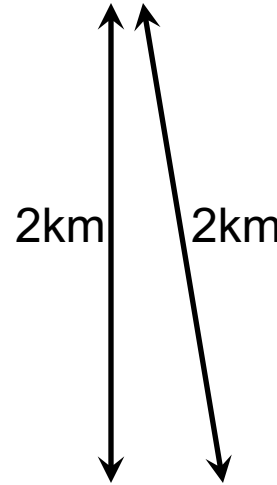
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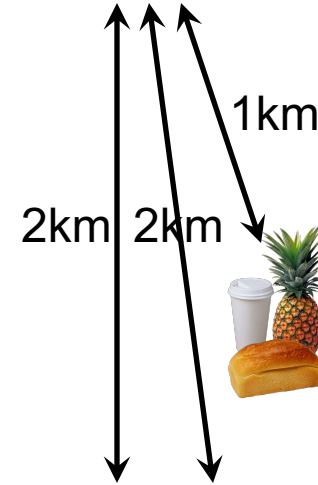
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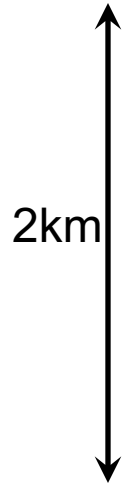
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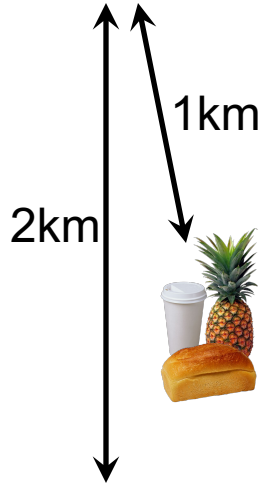
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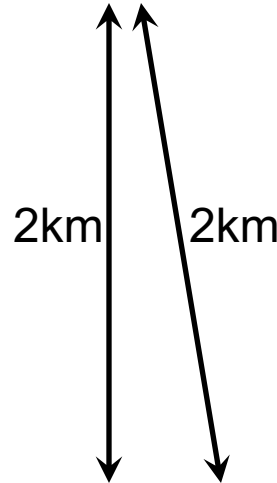


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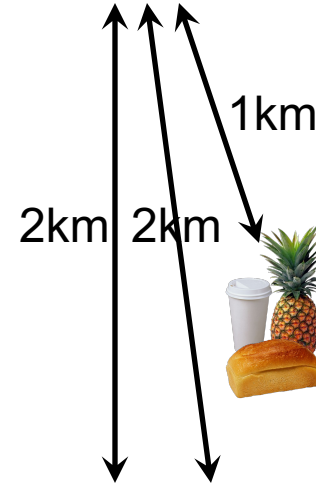
+1.313



$$A_i = \ln(e^{-2} + e^{-2})$$

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$$A_i = \ln(e^{-2} + e^{-2} + e^{-1})$$

$$= \ln(0.135 + 0.135 + 0.368)$$

$$= -0.449$$

+0.860

How does it work?

- Calculate accessibility A_i of a given origin location i to opportunity locations j
 - Origin location i and opportunity locations j are assigned to the road network
 - For every i , compute a least cost path tree
 - Find best route with least cost C_{ij} between i and j
 - Based on Dijkstra's algorithm
 - Includes cost of network access/egress
- For different modes: Free-speed car, time-dependent congested car, bicycle, public transport, etc.
- For different opportunity types: Shopping facilities, leisure facilities, workplace, etc.

Accessibilities integration in Dynamic Transport Simulation

Time dependencies

- Dynamic transport system characteristics
 - Individual transport: Congestion
 - Public transport: Schedule (+ congestion)
- Opening times of activity facilities

Data models and input data preparation procedures of MATSim

- Network generation based on OSM
- Facility generation based on OSM
- Public transport schedule generation based on GTFS

BERLIN AV/AT ACCESSIBILITY CASE STUDY

Case Study for Berlin

- Changes in terms of activity participation opportunities in a possible future transport system, which is more strongly reliant on autonomous cars
- Analysis Instrument: Accessibilities
- Accessibilities computed for
 - Public transport (schedule-based)
 - Autonomous cars that operate as mobility-as-a-service
 - Private car
- Accessibilities to education facilities at 8:00:00

Modeling assumption

- Waiting time has same (dis)utility as in-vehicle travel time (relevant for ATs and PT)
- Access/egress time and time to change vehicles as well (relevant for PT)
- AVs travel with same speeds (and same congestion) as 'regular' cars

Dynamics in the system

- Travel time depends on congestion (private cars and ATs)
- Waiting time until pick-up depends on demand and congestion (ATs)
- Dependency on PT schedule (PT)

AT operating rules

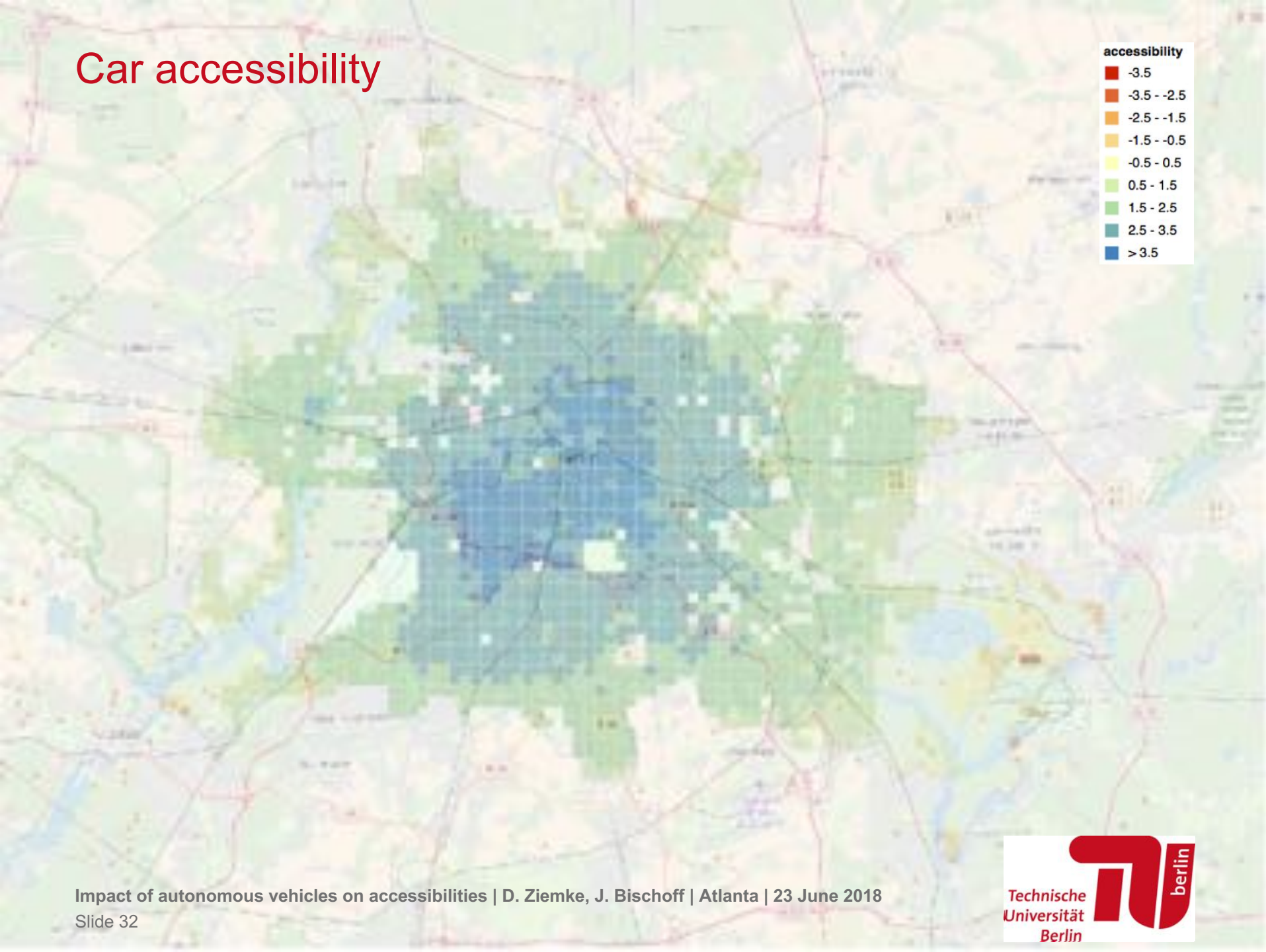
- Request
 - Dispatch the nearest idle taxi **OR** queue request
- Drop-off
 - Wait **OR** serve the nearest waiting request
- Destinations of AT trips unknown when trip requested
 - Waiting time origin-specific

Modeling AT pick-up times

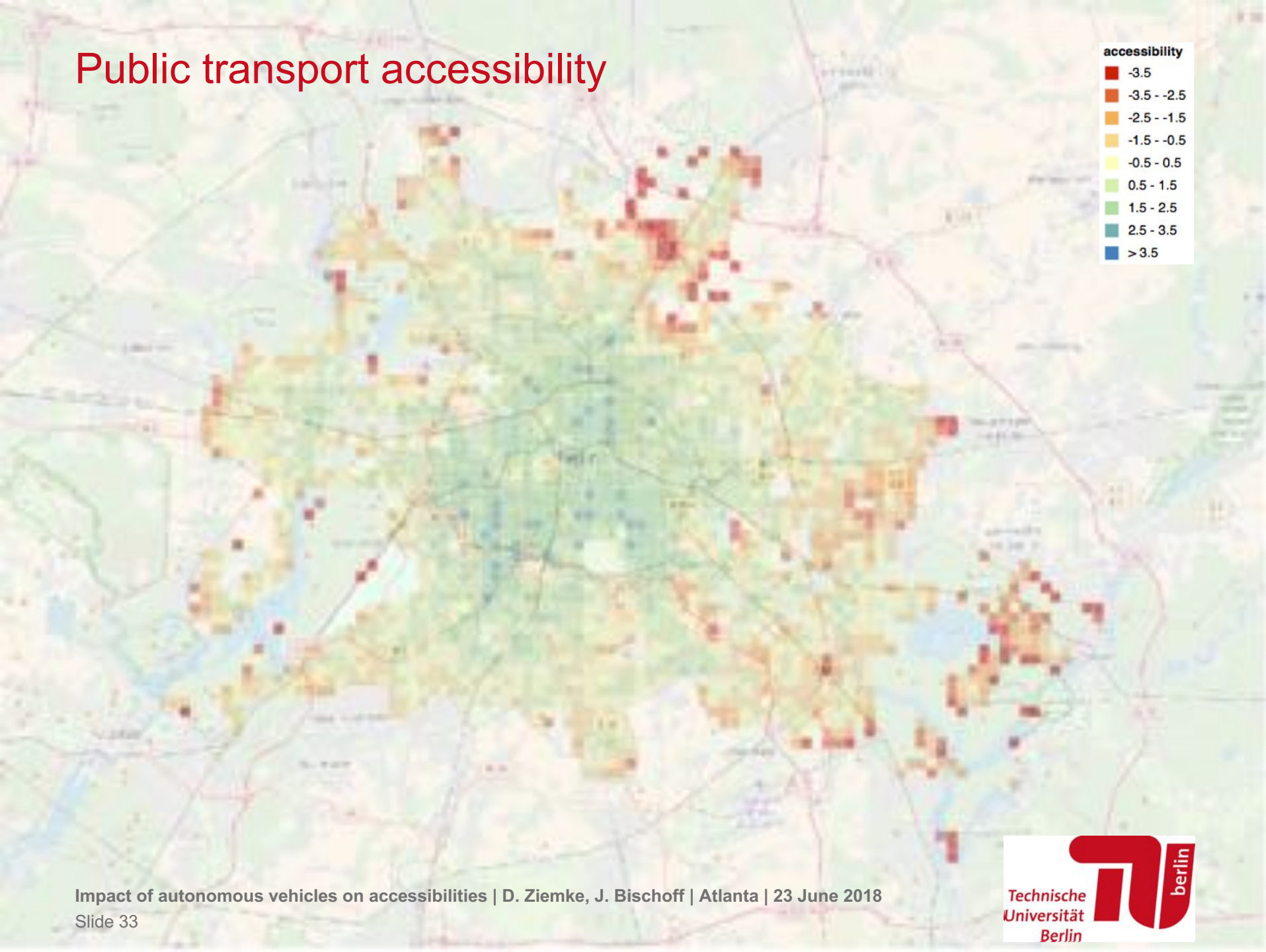
- MATSim Open Berlin Scenario
 - 10% of agents who travelled by PT before want to make their trip by AT
 - Measure pick-up/waiting time and assign to measure point of accessibility computation grid
 - Do this 10x (with different randomly chosen 10% of agents) and average
- Location-based, time-dependent AT pick-up times

RESULTS

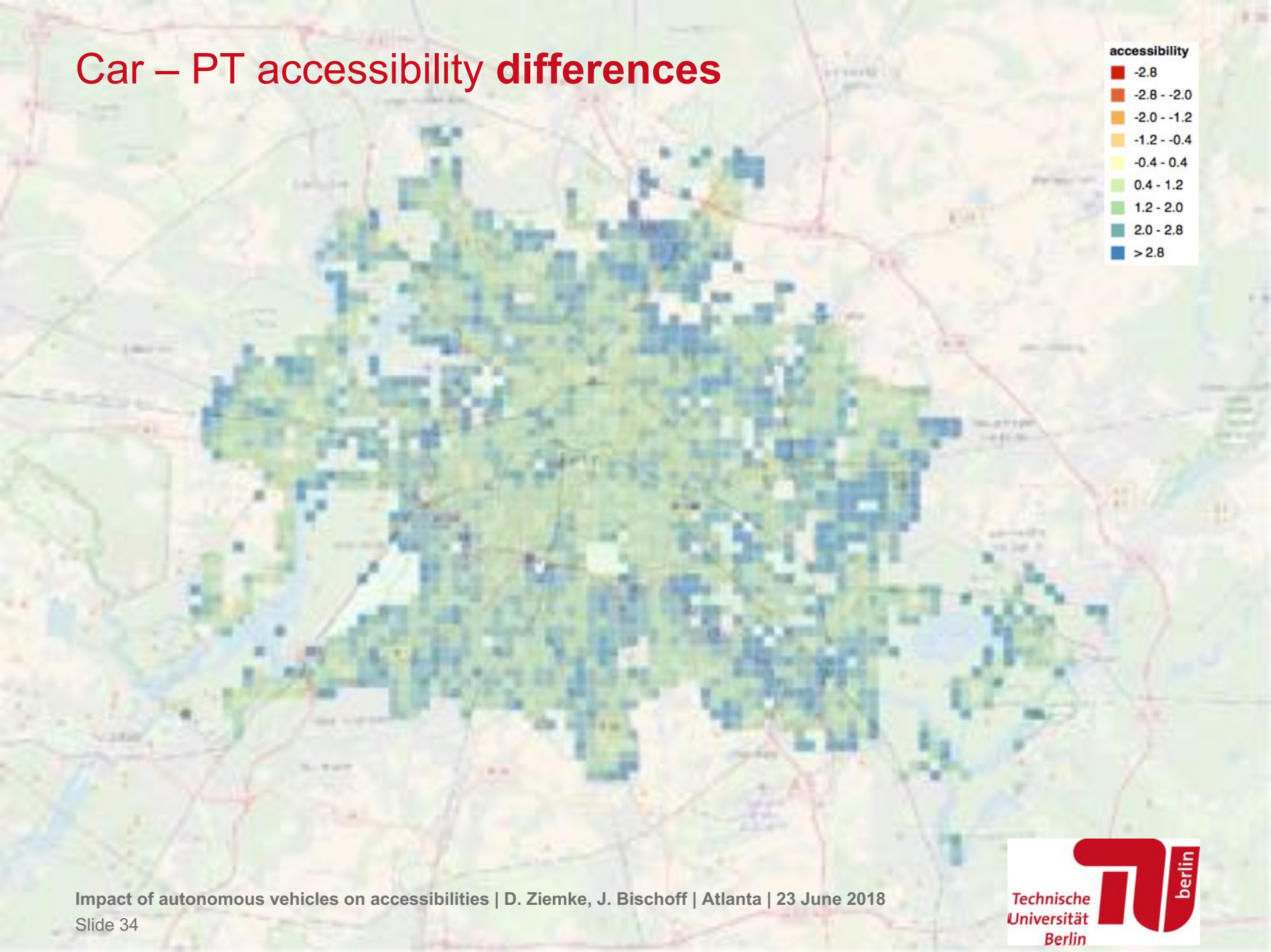
Car accessibility



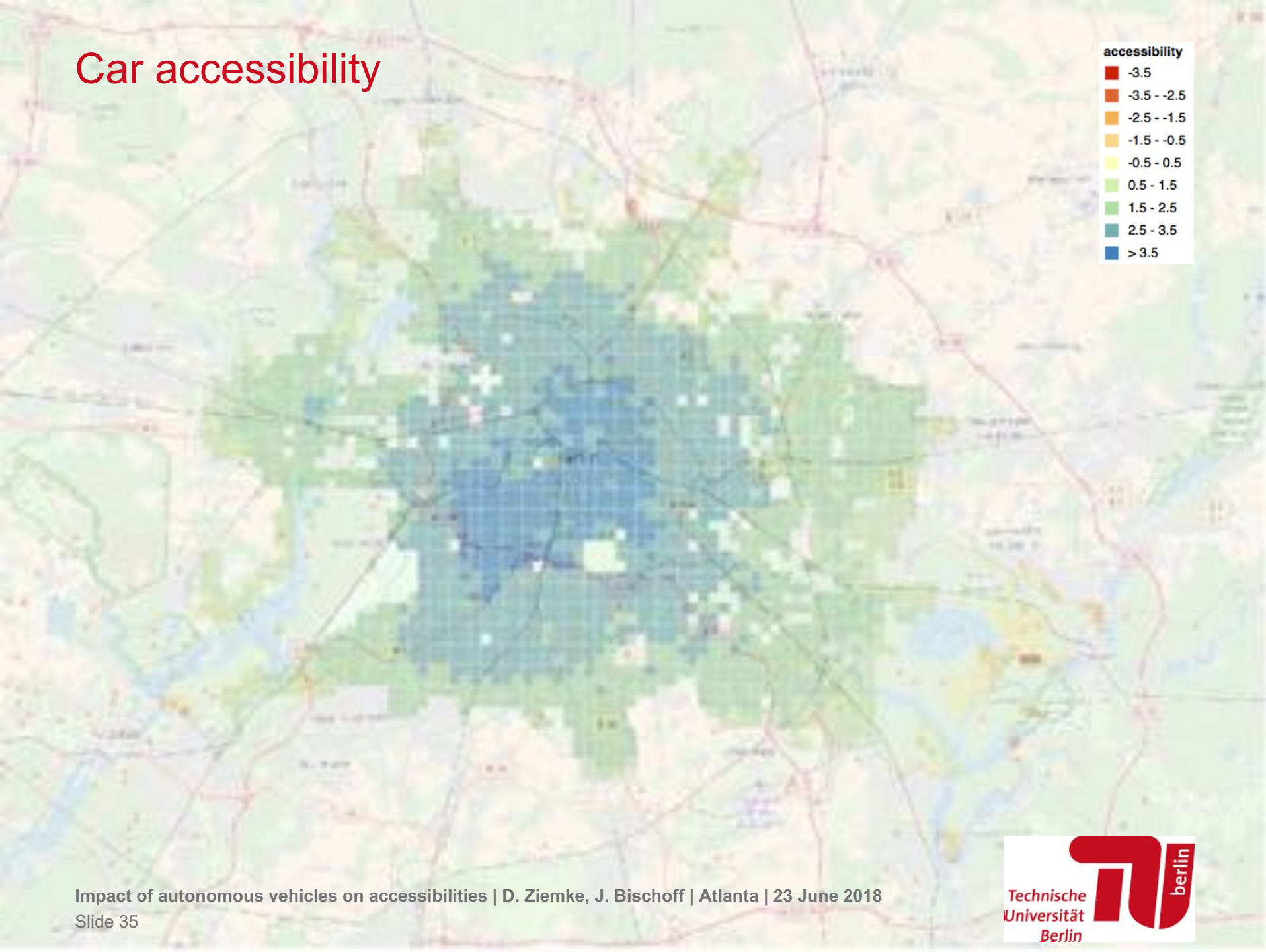
Public transport accessibility



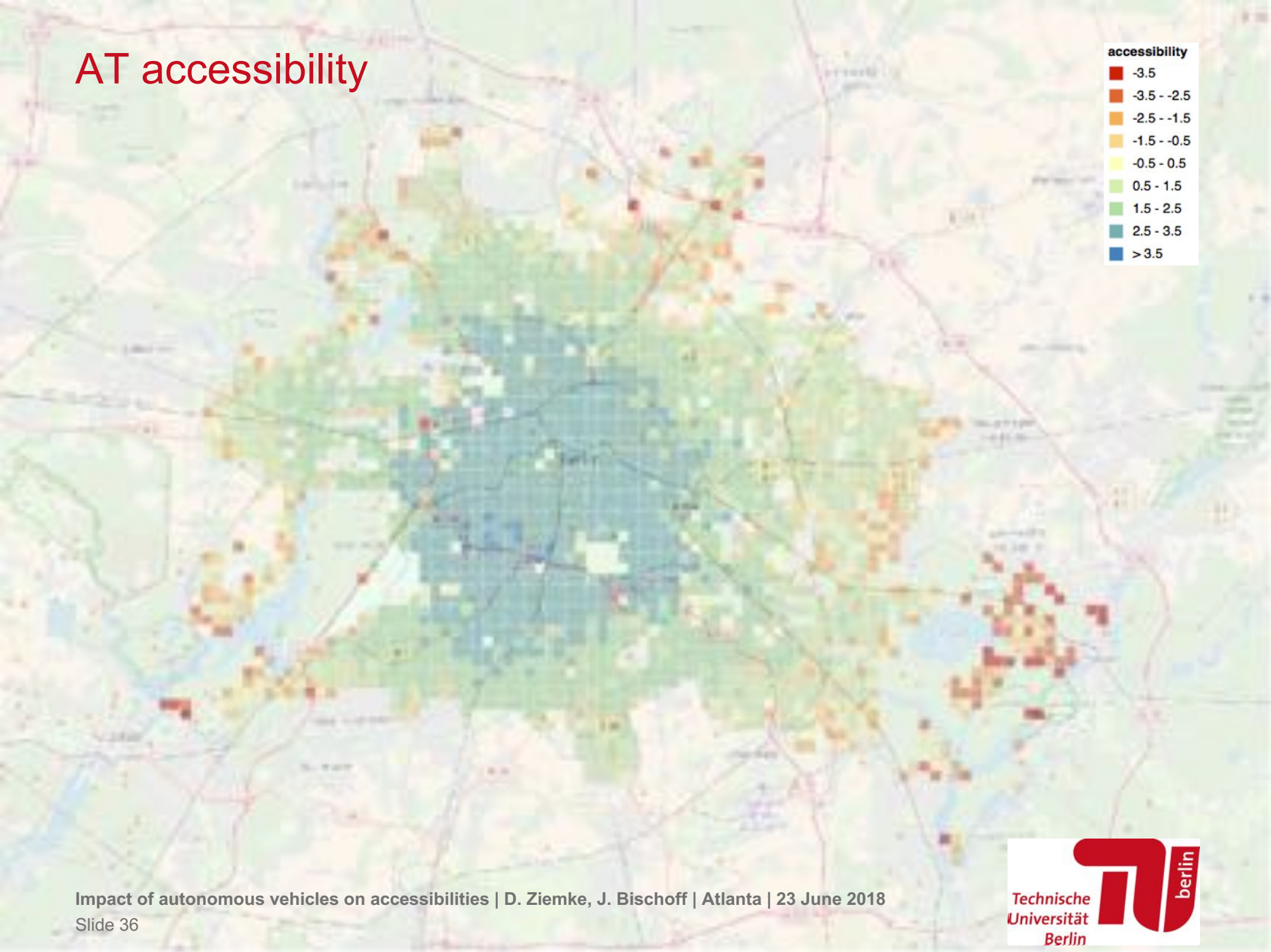
Car – PT accessibility differences



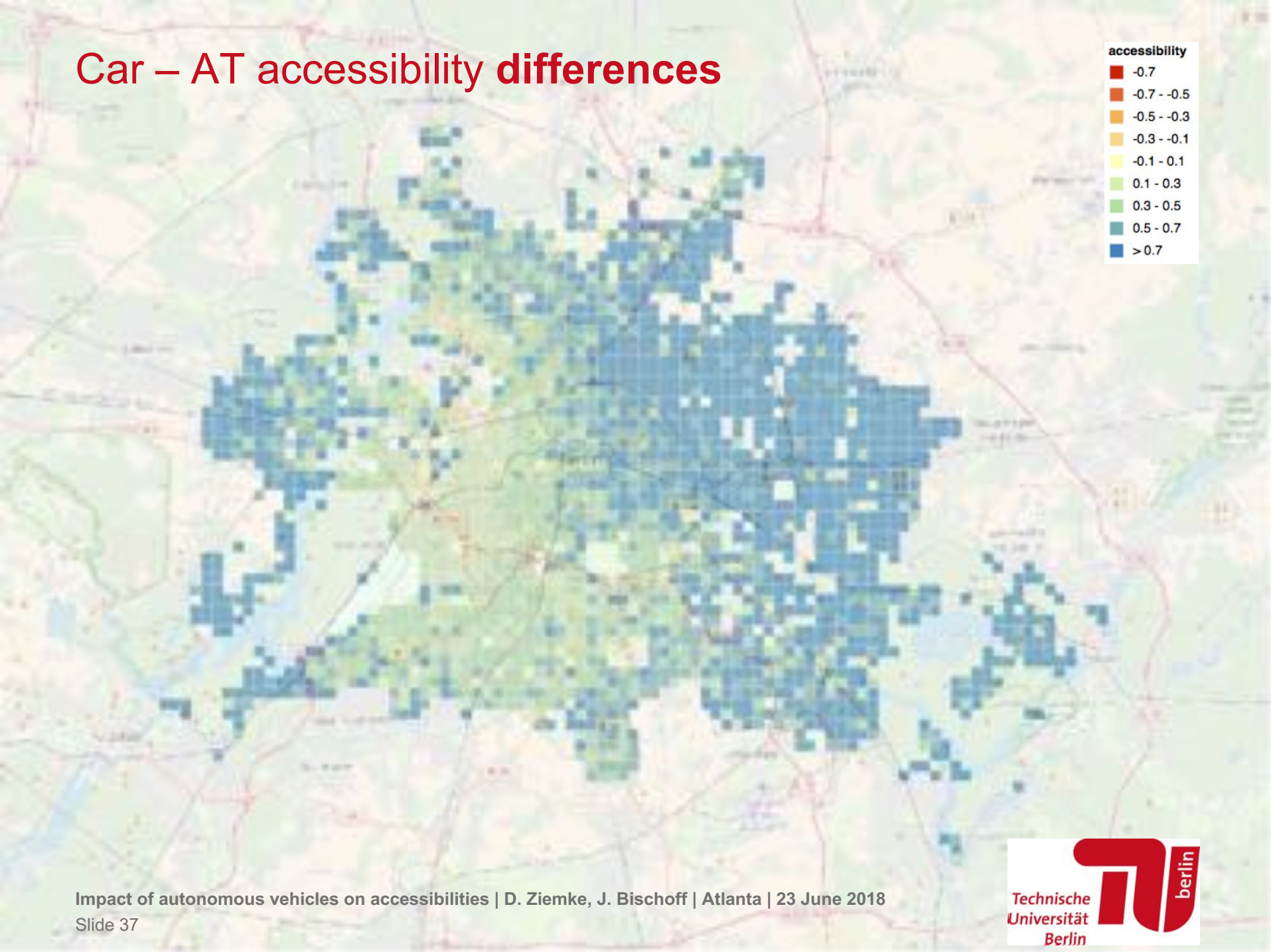
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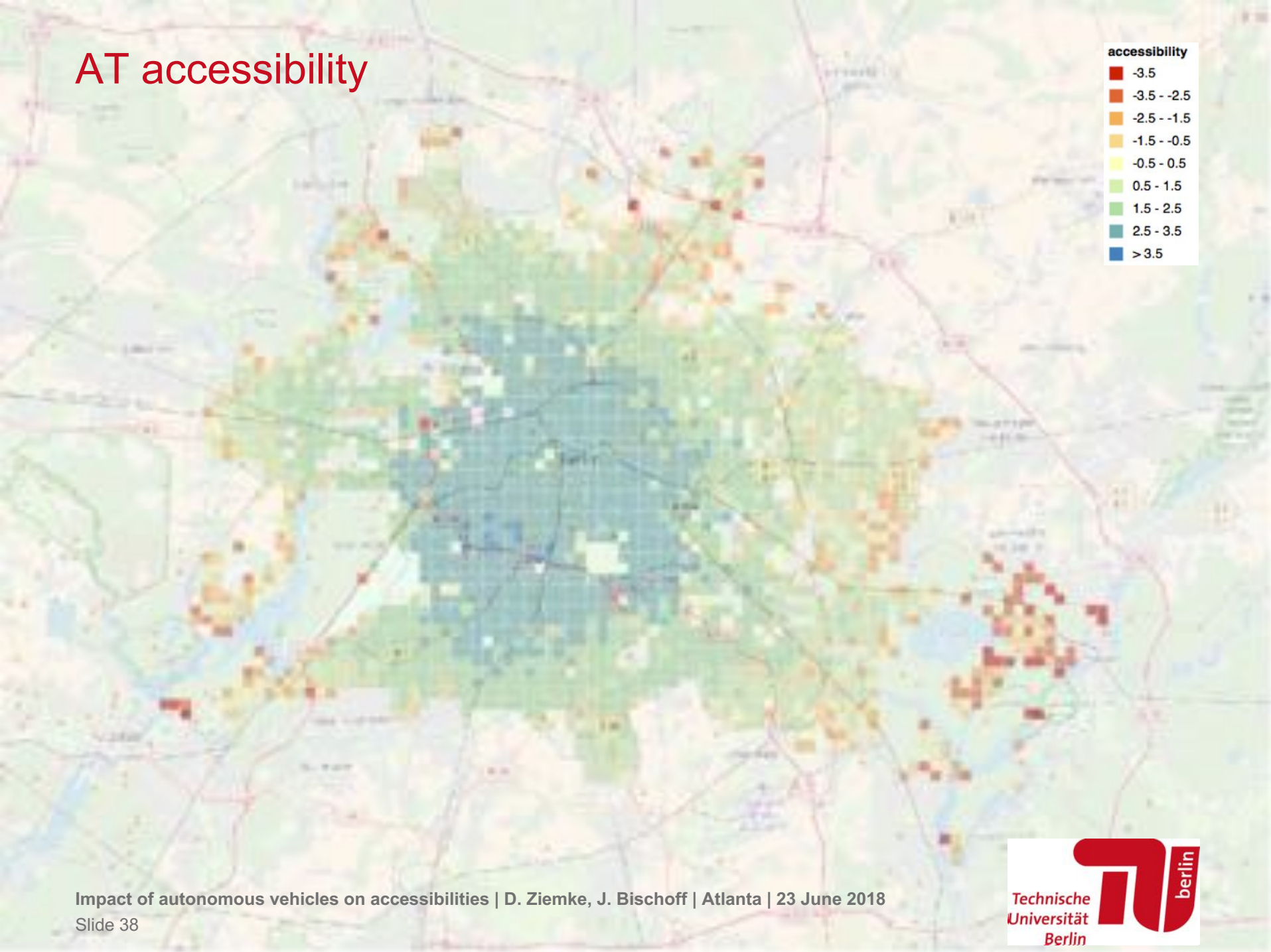
AT accessibility



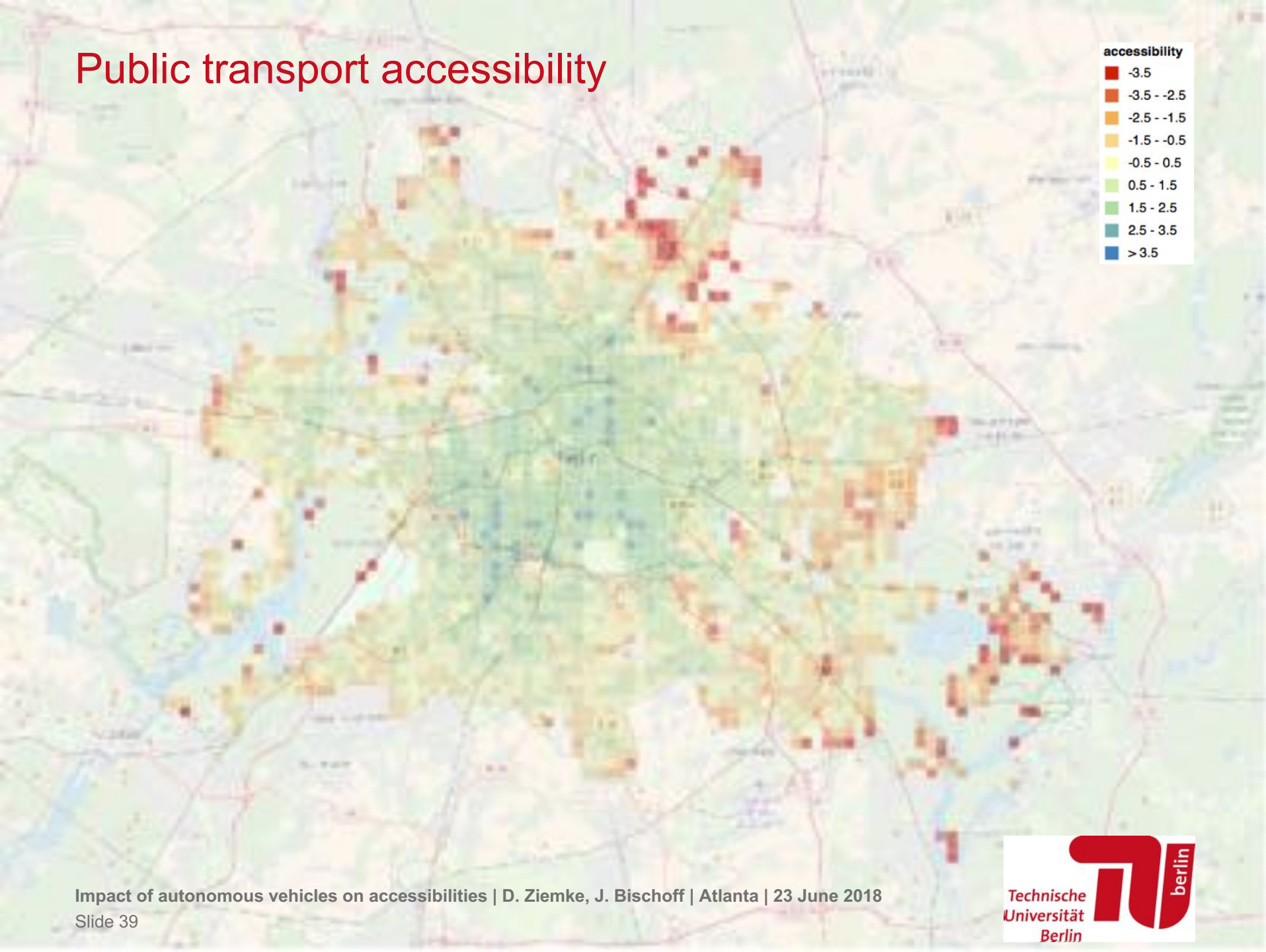
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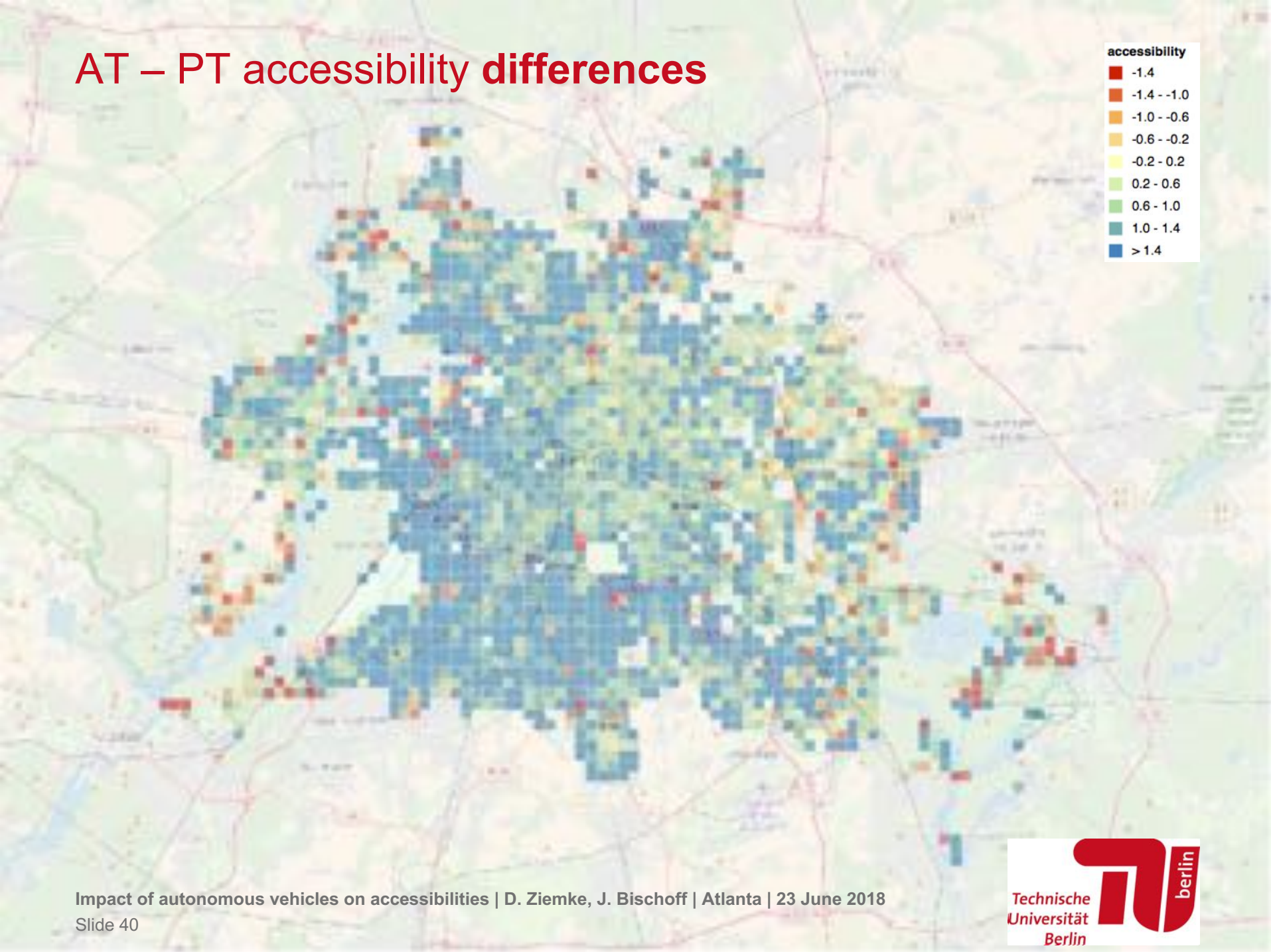
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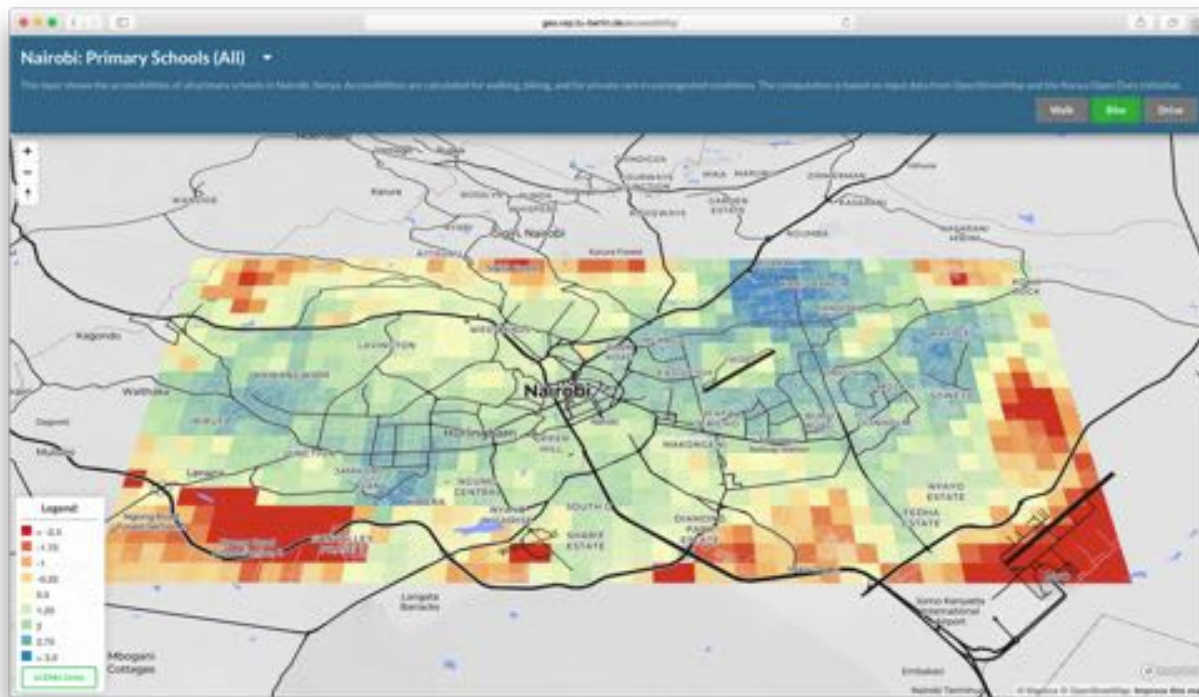


AT – PT accessibility differences



Some first findings

- Car-to-PT accessibility advantage small in city center
- AT accessibility between car and PT accessibility
- Car-to-PT accessibility advantage greater in the East
- AT-to-PT accessibility advantage greater in the West



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Thank you!